

MANUAL

Field current controller Q3-F



Hans-Paul-Kaysser-Straße 1
71397 Leutenbach-Nellmersbach

Tel.: 07195 / 92 83 - 0
contact@unitek.eu
www.unitek.eu

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Table of contents

1	General	2
1.1	Field current supply in thyristor controller Q3.....	2
2	Field current controller 0 - 10A	3
2.1	Potentiometer	3
2.2	Field current setting	3
3	Field release circuit.....	4
3.1	Potentiometer	4
3.2	Setting field detachment.....	4

1 General

1.1 Field current supply in thyristor controller Q3

The field current supply in the thyristor controller Q3 can be used as a field current controller or as a field release circuit for combined armature-field control.

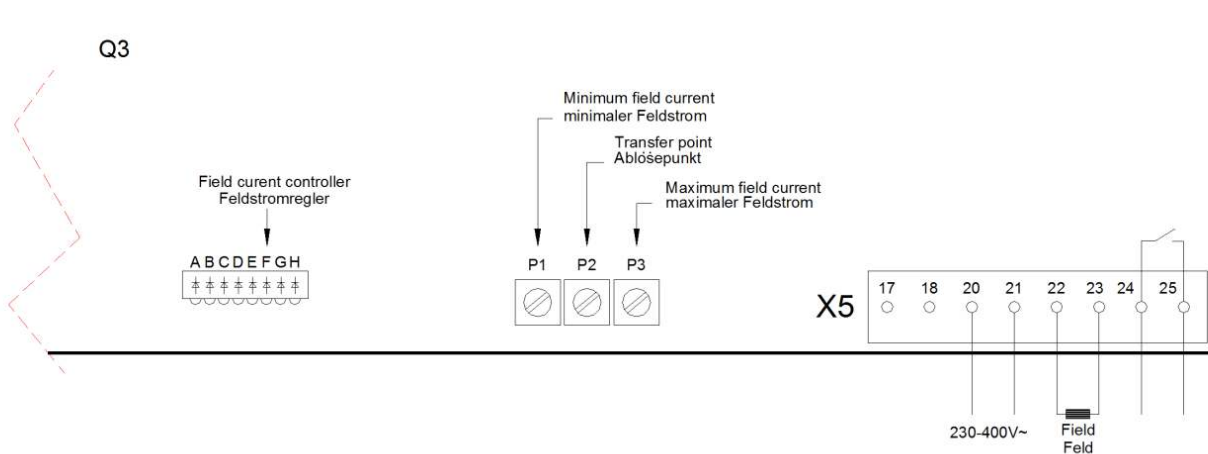
The field supply can be supplied separately with 230 V to 400 V at terminals X5:20, X5:21.

The field voltage at terminals X5:23+ and at X5:22- is max. 0.8 x input voltage.

The maximum field current is 10 A (depending on the unit type).

The field current is monitored and the signal relay is energised.

Contact at terminal X5:24 and X5:25 is closed and opens when the field current is lost.



2 Field current controller 0 - 10A

2.1 Potentiometer

Function	Abbreviation	Number
Minimum field current	Imin	P1
Maximum field current	Imax	P3
Right-hand stop	Abl.	P2

2.2 Field current setting

- Field circuit ammeter
- Enable controller, setpoint - zero.
- Potentiometer P2 to the right stop.
- Set the maximum field current with potentiometer P3.
- When the controller is locked, the field current is reduced to approx. 50 %.

Field release circuit

3 Field release circuit

3.1 Potentiometer

Function	Abbreviation	Number
Minimum field current	I _{min}	P1
Maximum field current	I _{max}	P3
Detachment point	Abl.	P2

3.2 Setting field detachment

- With enable, setpoint zero and motor at standstill, set the maximum field current with potentiometer P3.
- Set potentiometer P2 and potentiometer P1 to the right stop.
- Increase the engine speed until the armature tension is 5 % above the desired release point.
- Turn potentiometer P2 to the left until the armature voltage has dropped to the desired release voltage at constant speed.

Example:

- potentiometer P2 right stop.
 - Increase the speed setpoint on the motor controller until the armature voltage reaches 420 V.
 - Turn potentiometer P2 to the left until the armature voltage has dropped to 400 V.
 - The release point is now at 400 V armature voltage.
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- Increase the setpoint further and if the desired final speed is not reached, reduce the minimum field current by turning potentiometer P1 counterclockwise.
 - When the controller is locked, the field current is reduced to approx. 50 %.